Description, AN, Measurement Volume of Decagon Volumetric Water Content Sensors		Part # and Rev. 14955	
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Rev.	Description	Revision By	Date
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Decagon and Vendor Production Filename:

http://manuals.decagon.com/Application%20Notes/14955 VWC%20Sensor%20Measureme nt%20Volumes Web.pdf

Dimensions: 8.5 inch wide, 11 inch tall

Material: Paper, 92 Bright White or better, 75g/m² or heavier

Colors: Color Print on White

Printer: HP Color LaserJet 8550-PS

Finish: None

Adhesive: None

Special Notes: Illustrations are Ref Only ** Not to Scale **



Application Note

Measurement Volume of Decagon Volumetric Water Content Sensors by Doug Cobos

Introduction

One of the most important factors to evaluate when selecting a soil moisture sensor is the volume of soil that the sensor integrates into the volumeric water content (WC) measurement. For some applications, a sensor with a small measurement volume is desirable (e.g. greenhouse applications, near-surface measurements). However, in many field situations significant small-scale heterogeneity is present in the soil, meaning that a small volume measurement may not adequately reflect the average volumetric valet content at the measurement location. For many field applications a larger measurement volume minimizes these issues and yields a more representative measurement of the true WC. This Application Note describes the results of tests that were conducted to quantify the measurement volume of Decagon's WC sensors.

Nethods
The tests used to evaluate the measurement belowers of the Designs sensors were based on those in Sakaki et al. 2008, and are described here of the Designs need to those in Sakaki et al. 2008, and are described here briefly. Each VMC sensor was suspended in air in a stationary position using a ring stand and clamp. A plane of water wither-filled, flat-sided plastic container) was then incrementally brought horizontally toward the sensor while recording sensor output. The outer edge of the measurement volume was identified as the distance where the presence of the water change the sensor output appreciably. We repeated this process at six different sensor orientations to obtain a three-dimensional representation of the sensor measurement volume.

Results and Discussion
The sensor measurement volumes are encompassed by envelopes shown in Figures 1 through 8 below. If the measurement volume for

each sensor is approximated as an ellipsoidal cylinder with the dimensions measured experimentally, as Figures 1 to 8 demonstrate, then you can calculate the total measurement volumes in Table 1.

It is well known that the electric field distribution inside the measurement volume is strongly weighted toward the sensor surfaces. Care should still be laken to ensure good soil-sensor contact to avoid air gaps at the sensor surface where It is most sensitive. It is also likely that electromagnetic field lines propagate further horugh air than through higher dielectric material (i.e. soil), so the dimensions in Figures 1 through 8 and the volumes in Table 1 should be taken as the maximum possible for each sensor. They should be good guidelines for installing the sensors near the soil surface or near a foreign object in the soil.

Sakaki, Toshihiro, Limsuwat, Anuchit, Smits, Kathleen M., and Illangasekare, Tissa H. (2008). Empirical two-point a-mixing model for calibrating the ECH_0 EC-5 soil moisture sensor in sands. Water Resource Research, 44 4, W00D08.

support@decagon.com

509-332-2756 www.decagon.com